

Flat coalgebraic fixed point logics

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Coalgebraic Modal Logic

- Generic semantic framework
- Coverage of e.g.:
 - ▶ **K**, **KD**, *HML*
 - ▶ Graded modal logic: $\diamond_n \phi$ – “ ϕ holds in at least n successor states”
 - ▶ Probabilistic modal logic: $\diamond_p \phi$ – “there is a successor where ϕ holds with probability p ”
 - ▶ Coalition logic: $\square_C \phi$ – “coalition C can enforce ϕ ”
 - ▶ Conditional logics, *binary*: $\phi \Rightarrow \psi$ – “if ϕ then usually ψ ”
 - ▶ Basic description logics (e.g. **K** + global assumptions)
 - ▶ Fixed point logics (e.g. *AF* ϕ – “ ϕ holds eventually on all paths”)
- Generic complexity bounds, algorithms

Coalgebraic Modal Logic, ctd.

Set-endofunctor T , T -coalgebra $\mathcal{C} = (X, \xi)$, structure $\xi : X \rightarrow TX$.

Syntax

Modal operators $\Lambda \ni \heartsuit$:

$$CML(\Lambda) \ni A_1, \dots, A_n := \neg A_1 \mid A_1 \wedge A_2 \mid \heartsuit(A_1, \dots, A_n)$$

Semantics

Predicate Liftings ($[[\heartsuit]]_Y : (\mathcal{P}Y)^n \rightarrow \mathcal{P}TY$) $_{Y \in \text{Set}}$.

Satisfaction of modal operators (for $[[\phi]]_{\mathcal{C}} = \{c \in X \mid \mathcal{C}, c \models \phi\}$):

$$[[\heartsuit(A_1, \dots, A_n)]]_{\mathcal{C}} = \xi^{-1} \circ [[\heartsuit]]_X([[A_1]]_{\mathcal{C}}, \dots, [[A_n]]_{\mathcal{C}})$$

$$\mathbf{K}: \quad T = \mathcal{P}, \quad [[\Box]]_X(Y) = \{A \in \mathcal{P}(X) \mid A \subseteq Y\}, \\ [[\Diamond]]_X(Y) = \{A \in \mathcal{P}(X) \mid A \cap Y \neq \emptyset\}.$$

$$\mathbf{CK}: \quad T = CK, \quad CK(X) = \{f : \mathcal{P}(X) \rightarrow \mathcal{P}(X)\}, \\ [[\Rightarrow]]_X(Y, Z) = \{f \in CK(X) \mid f(Y) \subseteq Z\}.$$

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Deciding satisfiability

- A formula ϕ is **satisfiable** if there is a coalgebra $\mathcal{C} = (X, \xi)$ containing a state $x \in X$ s.t. $x \in \llbracket \phi \rrbracket_{\mathcal{C}}$.
Fact: ϕ is satisfiable iff $\neg\phi$ is not **valid**. Focus here: satisfiability.
- For rank-1 modal logics, validity may be decided coalgebraically in PSPACE [Schröder, Pattinson, 2009]; sequent calculus.
- EXPTIME if global assumptions are allowed; global caching algorithm [Goré, Kupke, Pattinson, 2010].
- EXPTIME if (flat) fixed point operators are allowed [Cirstea, Kupke, Pattinson, 2009; Schröder, Venema, 2010]; here: focusing global caching algorithm.

Tableau rules

$$(\neg\wedge) \frac{\Gamma, \neg(\neg A \wedge \neg B)}{\Gamma, A \quad \Gamma, B}$$

$$(\neg\neg) \frac{\Gamma, \neg\neg A}{\Gamma, A} \quad (\wedge) \frac{\Gamma, (A \wedge B)}{\Gamma, A, B}$$

Modal rule(s), e.g.:

$$(\neg\Box K) \frac{\Gamma, \bigwedge_{i=1}^n \Box A_i, \neg \Box B}{\bigwedge_{i=1}^n A_i, \neg B} \quad (\Rightarrow CK) \frac{\Gamma, \bigwedge_{i=1}^n (A_i \Rightarrow B_i), \neg(A_0 \Rightarrow B_0)}{\bigwedge_{i=1}^n A_{i-1} \not\Rightarrow A_i \quad \bigwedge_{i=1}^n B_i, \neg B_0}$$

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Tableau Algorithm

Tableau system

Apply all tableau rules, depth first search.

A set of formulae Γ is successful if for all (\forall) rule applications to Γ there is (\exists) a premise which is successful.

- + Generic and realizes PSPACE proof search.
- Not particularly open to optimisations, per se not capable of treating global assumptions. Thus:

Global Caching

Construct a two-kinded *proof graph* which employs tableau rules.
Propagate provability status through the graph.

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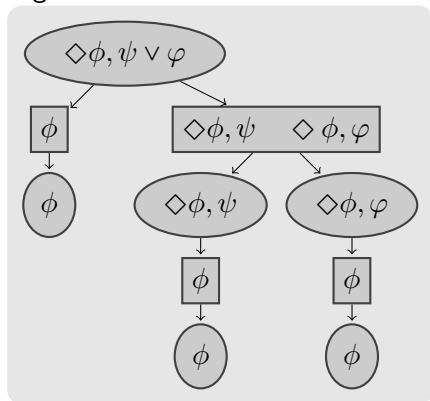
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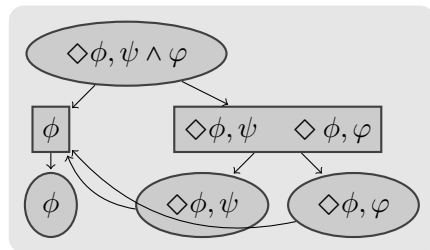
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Caching

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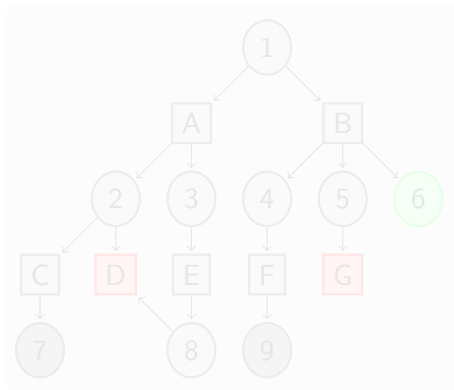


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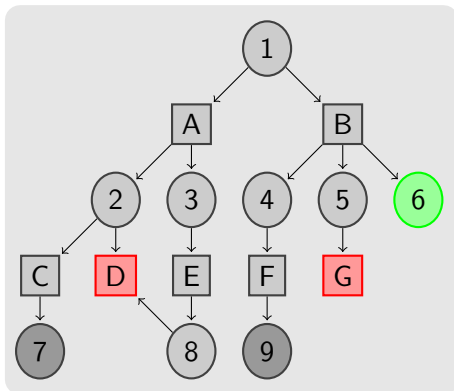


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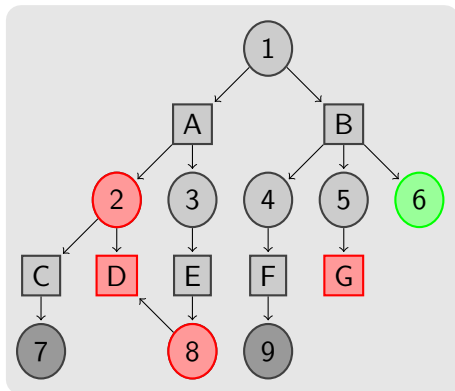


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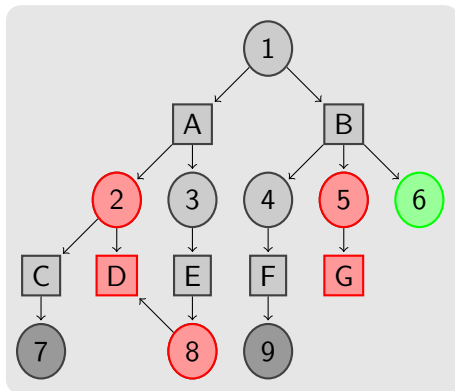


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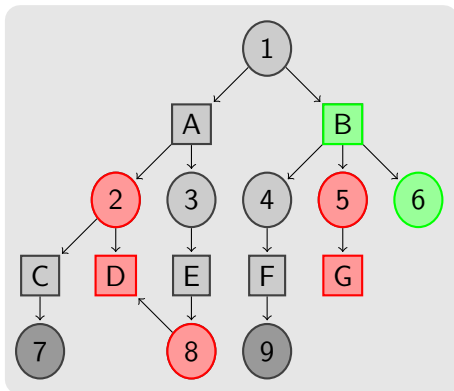


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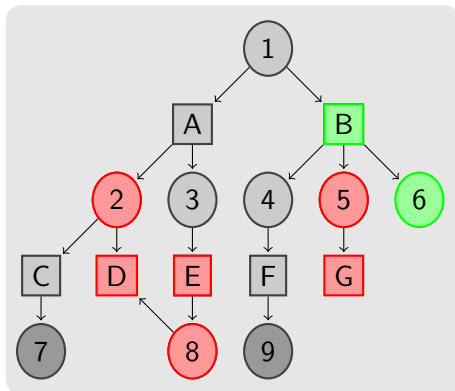


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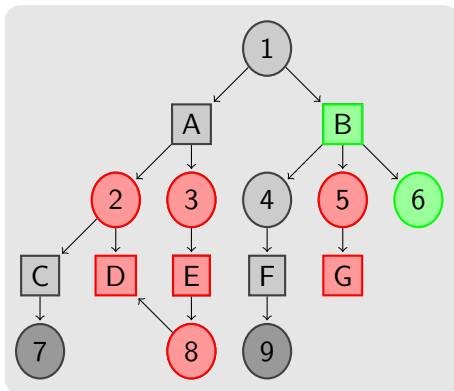


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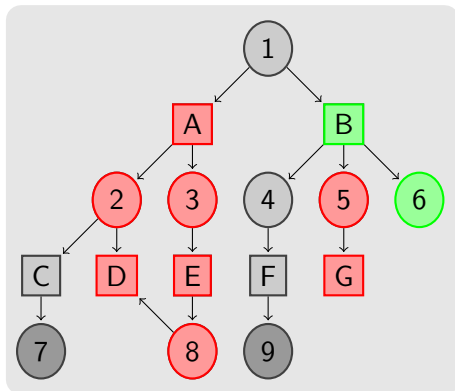


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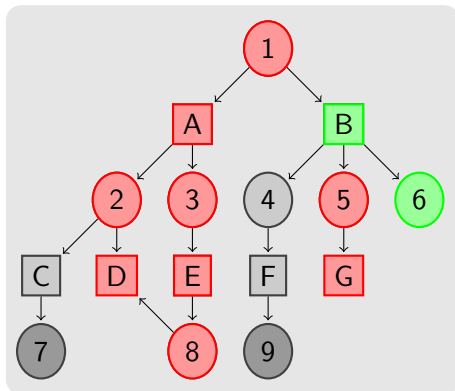


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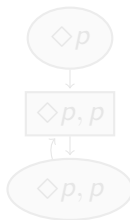


Global Assumptions

Extend *modal* rules by set of *global assumptions* $\Delta \subseteq \mathcal{CML}(\Lambda)$:

$$\boxed{\frac{\Gamma}{\Gamma_0, \dots, \Gamma_n}} \rightsquigarrow \boxed{\frac{\Gamma}{(\Delta \cup \Gamma_0), \dots, (\Delta \cup \Gamma_n)}}$$

E.g. $\Delta = \{\diamond p\}$:

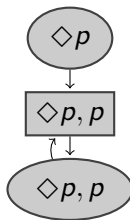


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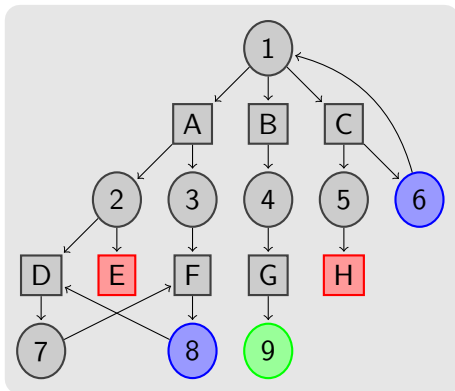
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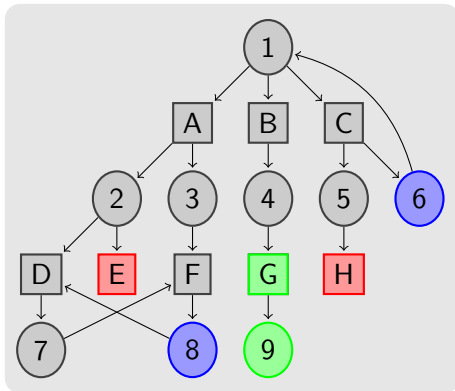
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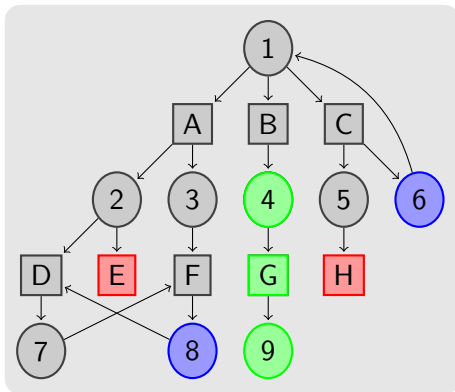
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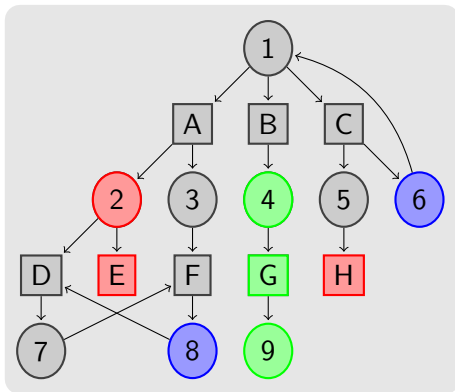
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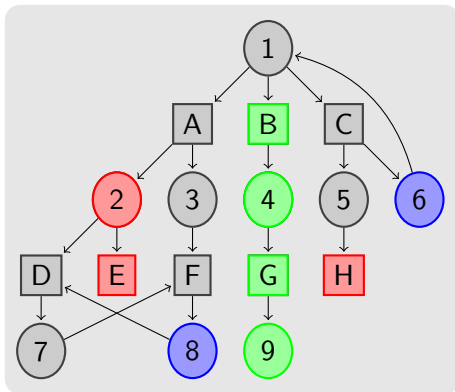
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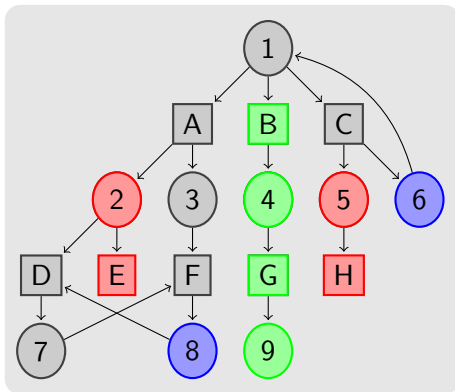
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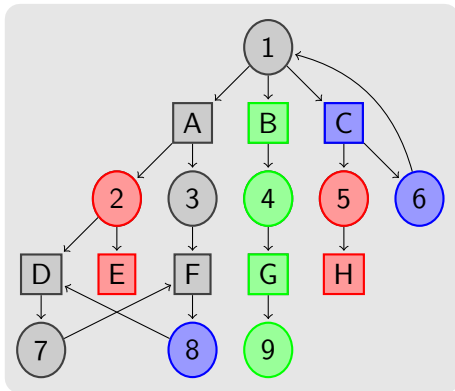
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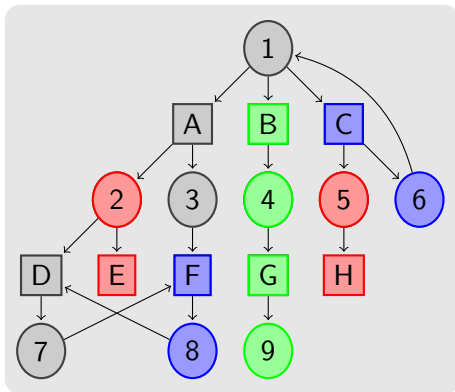
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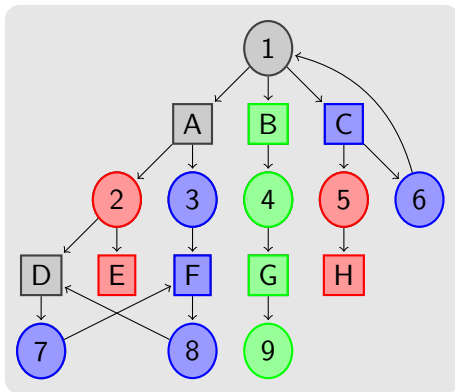
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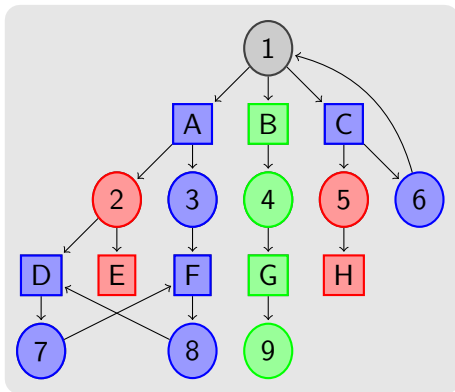
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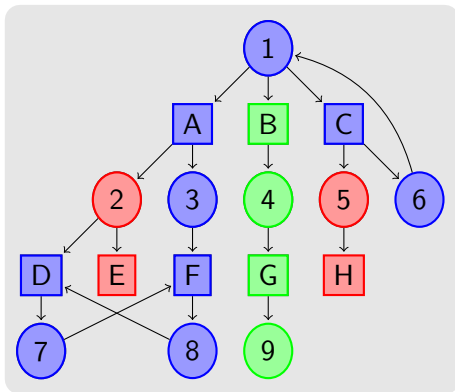
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$$G' = G \cup \nu(R^{\forall\exists}_E)$$

$$R^{\forall\exists}_Y(X) = \{\Gamma \mid \forall \Sigma. \Gamma \rightarrow \Sigma. \exists \Gamma' \in \Sigma. \Gamma' \in X \cup Y\}$$

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Efficient gfp-propagation

Let C be a set of *circular nodes* and let $R_Y^{Q\bar{Q}} \in \{R_Y^{\forall\exists}, R_Y^{\exists\forall}\}$.

$$\Theta_C^0(R_Y) = \mu(R_Y)$$

$$\Theta_C^{n+1}(R_Y) = \mu(R_{Y \cup \text{cgg}(R_Y, C_{n+1}, \Theta_C^n(R_Y))})$$

where $\text{cgg}(R_Y, C_{n+1}, \Theta_C^n(R_Y))$ computes *closed circular graphs* over C_{n+1} and $\Theta_C^n(R_Y)$.

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Let n be the number of strongly connected components in a proof graph. Then

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Flat fixed point logics

- **Depth-1** fixed point schemes

$$\mathcal{FPS} \ni \gamma_1, \gamma_2 ::= v \mid x \mid \gamma_1 \wedge \gamma_2 \mid \gamma_1 \vee \gamma_2 \mid \heartsuit \gamma_1.$$

- Add **flat** fixed point operators $\nu \gamma \psi$, $\mu \gamma \psi$ with $\llbracket \nu \gamma \psi \rrbracket_C = \nu \llbracket \gamma \psi \rrbracket$ where $\llbracket \gamma \psi \rrbracket(Y) = \llbracket \gamma[x/\psi, v/\phi] \rrbracket_C$ with $\llbracket \phi \rrbracket_C = Y$.

Examples

- PLTL: $\mathcal{I}(X) = X$, \mathcal{I} -coalgebras are ω -sequences.

$$\text{Predicate lifting } \llbracket \Box \rrbracket_C(X) = X, \psi_1 U \psi_2 \hat{=} \mu(x_2 \vee (x_1 \wedge \Box v))(\psi_1, \psi_2).$$

- CTL: For base logic \mathbf{K} , $A\psi_1 U \psi_2 \hat{=} \mu(x_2 \vee (x_1 \wedge \Box v))(\psi_1, \psi_2)$.

- ATL: $\mathcal{G}(X) = \{(S_1, \dots, S_n, f) \mid \emptyset \neq S_i \in \mathbf{Set}, f : \prod_{i \in N} S_i \rightarrow X\}$.

\mathcal{G} -coalgebras are *game frames*. Predicate lifting

$$\llbracket [D] \rrbracket_C(X) = \{(S_1, \dots, S_n, f) \in \mathcal{G}(C) \mid \exists s_D \in S_D. \forall s_{\bar{D}} \in S_{\bar{D}}. f(s_D, s_{\bar{D}}) \in X\}$$

Define $\llbracket \langle D \rangle \rrbracket \psi_1 U \psi_2 \hat{=} \mu(x_2 \vee (x_1 \wedge [D]v))(\psi_1, \psi_2)$.

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How to decide circular subgraphs?

$$\begin{array}{c}
 \frac{EpU(q \wedge \bar{q})}{(v) \frac{(q \wedge \bar{q}) \vee (p \wedge \diamond EpU(q \wedge \bar{q}))}{(q \wedge \bar{q}) \quad (p \wedge \diamond EpU(q \wedge \bar{q}))}} \\
 \frac{q, \bar{q}}{\downarrow} \quad (\diamond) \frac{p, \diamond EpU(q \wedge \bar{q})}{\Gamma := EpU(q \wedge \bar{q})}
 \end{array}$$

$$\begin{array}{c}
 \frac{AF\phi, \diamond EGAF\phi}{(v) \frac{\phi \vee \square AF\phi, \diamond EGAF\phi}{(\diamond) \frac{\phi, \diamond EGAF\phi}{EGAF\phi} \quad (\diamond) \frac{\square AF\phi, \diamond EGAF\phi}{AF\phi, EGAF\phi}}} \\
 \frac{\Gamma_1 := AF\phi, \diamond EGAF\phi}{\Gamma_2 := AF\phi, \diamond EGAF\phi}
 \end{array}$$

Treating eventualities

Solution: Focusing [Brünnler, Lange, 2008].

Global caching algorithm over **focused** pre-states $\Gamma : \mu\gamma\psi$.

Focus-respecting unfolding of lfps via technical construction Σ_{γ}^{ψ} , e.g.

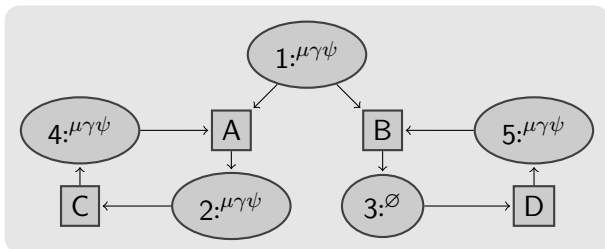
$$\Sigma_{x_2 \vee (x_1 \wedge \square v)}^{ApUq} = \{ \{p, q\} : \emptyset, \{q, \square ApUq\} : ApUq \}$$

$(\nu\text{UNF}) \quad \frac{\Gamma, \nu\gamma\psi : \text{foc}}{\Gamma, \gamma[x/\psi, v/\nu\gamma\psi] : \text{foc}}$	$(\text{FOC}) \quad \frac{\Gamma, \mu\gamma\psi : \emptyset}{\Gamma, \mu\gamma\psi : \mu\gamma\psi}$
$(\mu\text{UNF}) \quad \frac{\Gamma, \mu\gamma\psi : \text{foc}}{\Gamma, \gamma[x/\psi, v/\mu\gamma\psi] : \text{foc}}$	$(\mu\text{UNF}^f) \quad \frac{\Gamma, \mu\gamma\psi : \mu\gamma\psi}{\Gamma, \Sigma_{\gamma}^{\mu\gamma\psi}}$
$\emptyset \neq \text{foc} \neq \mu\gamma\psi$	

Focused propagation

$E' = E \cup \Theta_{C_\emptyset}^n (R_E^{\forall\exists})$, unfocused circular nodes C_\emptyset

$A' = A \cup \Theta_{C_\alpha}^n (R_A^{\exists\forall})$, focused circular nodes C_α



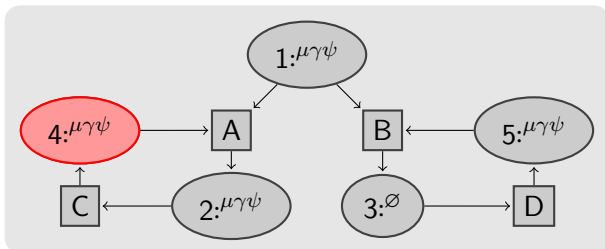
Proposition

The focusing global caching algorithm correctly decides the validity problem of depth-1 flat coalgebraic fixed point logics.

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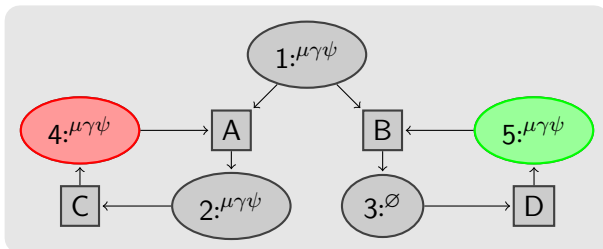
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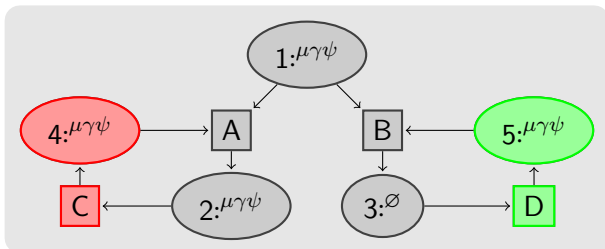
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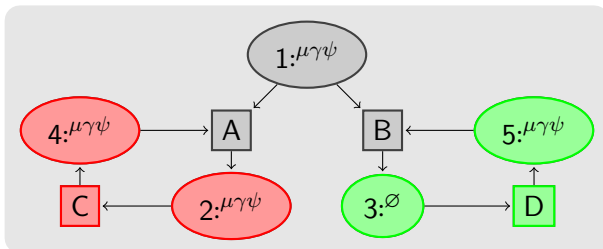
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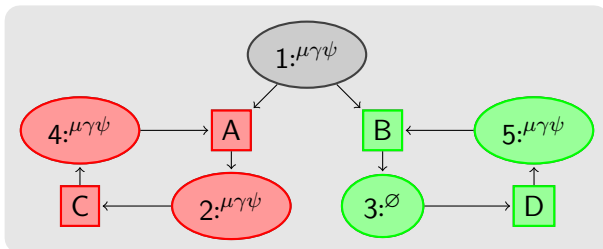
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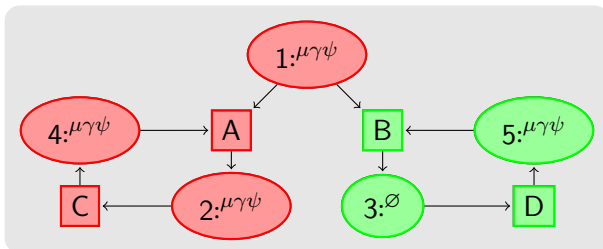
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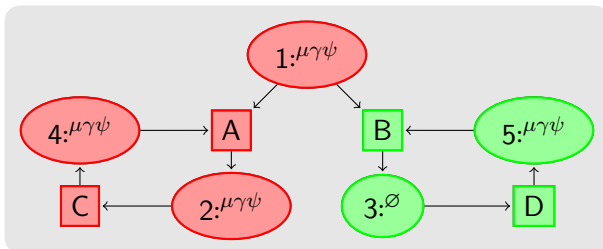
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The focusing global caching algorithm correctly decides the validity problem of depth-1 flat coalgebraic fixed point logics.

Model construction

Given $\mathcal{C} = (X, \xi)$, a pair $(x, \xi(x))$ is *coherent* if

$$\heartsuit\phi \in x \text{ iff } \xi(x) \in [[\heartsuit]]_x [[\phi]]_{\mathcal{C}}.$$

Existence Lemma

Coherent coalgebra $\mathcal{C} = (X, \xi)$ exists over *pre-tableaux* (which may be extracted from the proof graph constructed by the algorithm).

- Coherence does not ensure satisfaction of eventualities $\mu\gamma\psi$.

Truth Lemma

If the algorithm is successful, $\forall \mu\gamma\psi. \widehat{[[\mu\gamma\psi]]_{\mathcal{C}}} \subseteq \mu \widehat{[[\gamma\psi]]_{\mathcal{C}}}$.

- This yields a model, the crucial part for correctness, but it is a **big** model.

Small model lemma

Fisher-Ladner closure $\mathcal{FL}(\phi)$ is the least set containing ϕ and closed under negation, subformulae and unfolding of fixed points.

Set of all *maximal consistent sets* $MCS(S)$, $x \in MCS(S)$ if x is consistent and $S \ni \psi \notin x$ implies that $x \cup \{\psi\}$ is inconsistent.

Fact

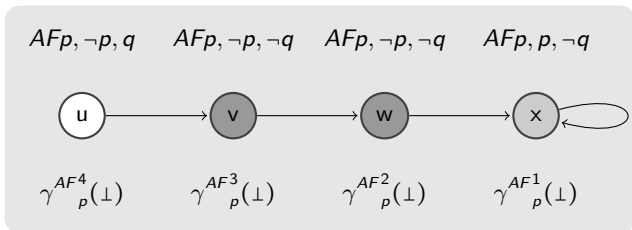
$$|MCS(\mathcal{FL}(\phi))| \leq 2^{|\phi|_m}.$$

Annotate the model $\mathcal{C} = (X, \xi)$ from Existence Lemma with unfoldings s.t.

$$\gamma_\psi^n(\perp) \in x \text{ iff } \mathcal{C}, x \models \gamma_\psi^n(\perp).$$

The reduction $r : Y \rightarrow MCS(\mathcal{FL}(\phi))$ is defined as $r(y) = y \cap \mathcal{FL}(\phi)$ (*Tr* follows).

Interior states

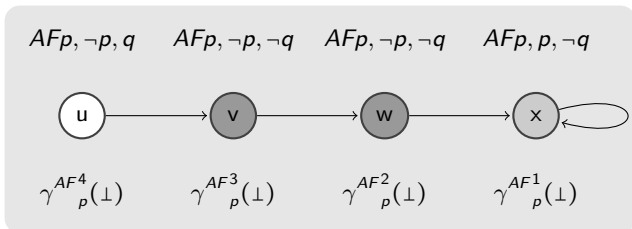


State x **interior** if there is $\mu\gamma\psi \in x$ and $m > 0$ s.t. $\mathcal{C}, x \models \overline{\gamma}_{\psi}^m(\wedge r(x))$.

E.g. $\overline{\gamma}_{\overline{p}}^{AF1}(\wedge(v)) = \neg p \wedge \diamond(\wedge r(v))$, $r(v) = r(w) = AFp, \neg p, \neg q$

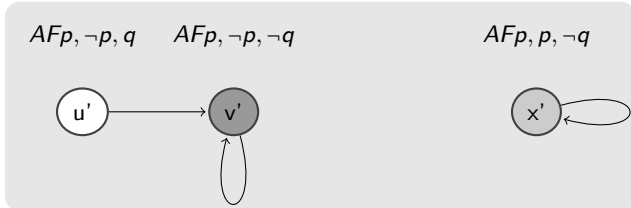


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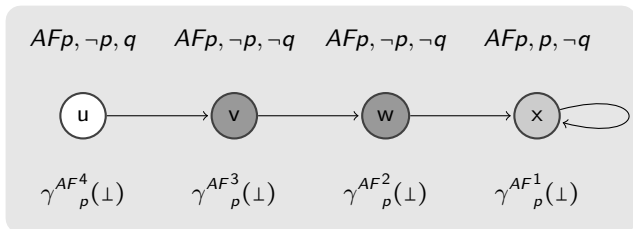


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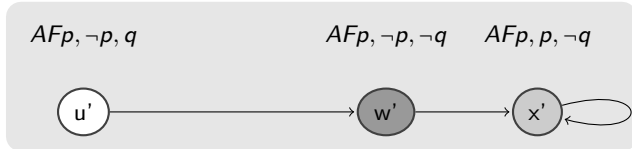


Interior states, ctd.

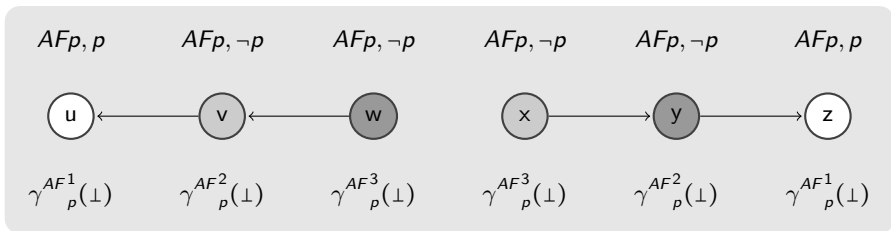


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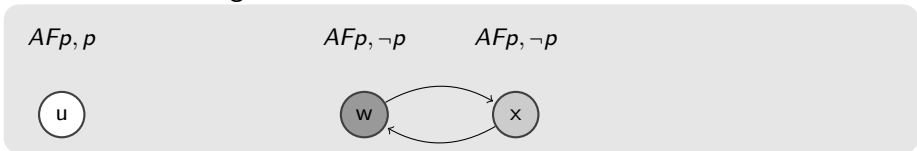
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Minimal states



State x is **minimal** if there is no state y with $r(y) = r(x)$ s.t. y has a lesser *eventual* degree than x .



Minimal states, ctd.

AFp, p

$AFp, \neg p$

$AFp, \neg p$

$AFp, \neg p$

$AFp, \neg p$

AFp, p



$\gamma^{AF^1_p}(\perp)$

$\gamma^{AF^2_p}(\perp)$

$\gamma^{AF^3_p}(\perp)$

$\gamma^{AF^3_p}(\perp)$

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AFp, p

$AFp, \neg p$

$AFp, \neg p$



Final links

$\mathcal{C} = (X, \xi)$ is **apt** (w.r.t. $\mathcal{D} = (Y, \zeta)$) if $r(y) = x$ and $Tr(\zeta(y)) = \xi(x)$ imply that y is minimal (and interior).

Lemma

Let ϕ be satisfiable. Then there is an apt coalgebra $\mathcal{C} = (X, \xi)$ over $X = MCS(\mathcal{FL}(\phi))$.

Lemma

The reduction $r : Y \rightarrow X$ preserves coherence. If $\mathcal{C} = (X, \xi)$ is apt w.r.t. $\mathcal{D} = (Y, \zeta)$, r also preserves satisfaction of $\gamma_{\psi}^n(\perp)$.

Together with Lindenbaum: for each $x \in X$, $\mu\gamma_{\psi} \in x$ there is an n s.t. $\mathcal{C}, x \models \gamma_{\psi}^n(\perp)$, i.e. each apt $\mathcal{C} = (X, \xi)$ is a model.

Small Model Lemma

Let ϕ be a *satisfiable* depth-1 fixed point formula. Then there is a model $\mathcal{C} = (X, \xi)$ over $X = MCS(\mathcal{FL}(\phi))$ (i.e. of size at most $2^{|\phi|_m}$).

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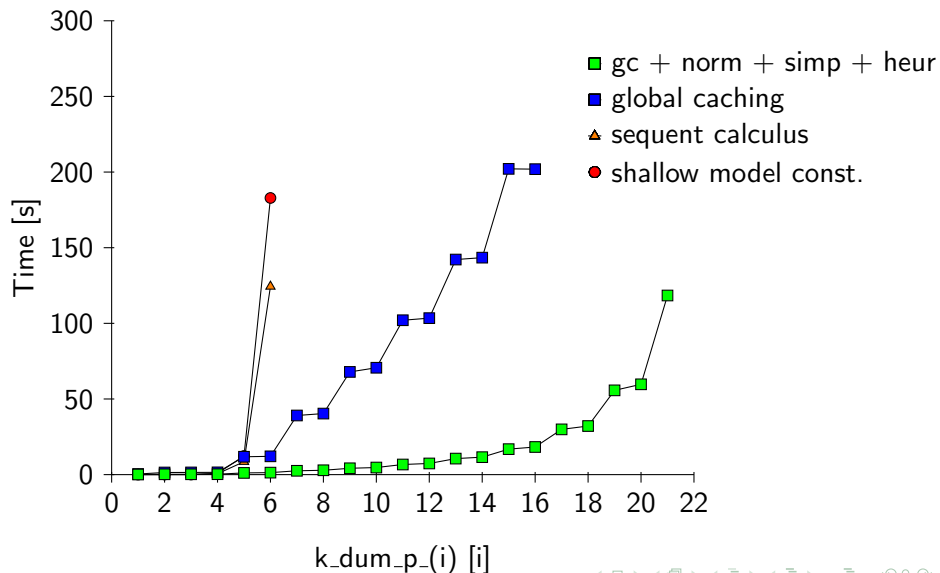
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Coalgebraic *Logic Satisfiability Solver* (CoLoSS); haskell implementation of generic sequent algorithm, (basic) generic global caching algorithm.

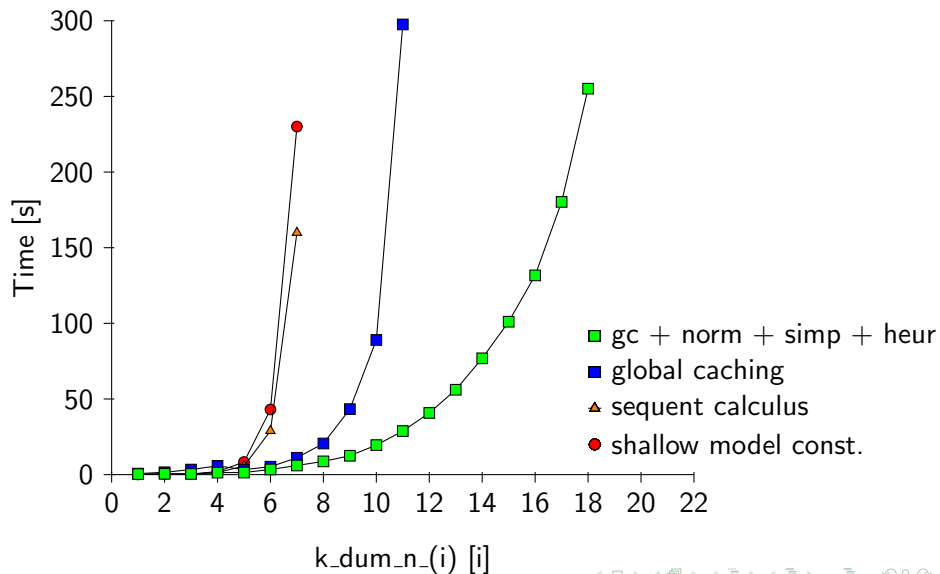
- Basic optimisations: Normalisation, simplification
- No global caching: Generalized **semantic branching** and generalized **dependency directed backtracking** are admissible
- **Heuristics** (*Most-often first, oldest first*)

<http://www.informatik.uni-bremen.de/cofi/CoLoSS/>

Benchmarking, k_dum_p, Tableaux 98



Benchmarking, k_dum_n , Tableaux 98



Conclusion / Future Work

- Consistency of coalgebraic modal logics by tableau algorithm.
- Treatment of global assumptions and fixed point logics by global caching algorithms.
- Efficient propagation by iterative approximation of gfps.
- Small ($2^{|\phi|_m}$) Model Lemma for depth-1 flat fixed point logics [Emerson, Halpern, 1985: $|\phi|_m(8^{|\phi|_m})$; Cirstea, Kupke, Pattinson, 2009: $2^{p|\phi|_m}$].
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